KiCad
The KiCad Team
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Referenz Handbuch

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Alle Markenrechtsnamen in diesem Guide gehören den rechtmäßigen Eigentümern.

Beitragende

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Übersetzung

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Feedback

The KiCad project welcomes feedback, bug reports, and suggestions related to the software or its documentation. For more information on how to submit feedback or report an issue, please see the instructions at https://www.kicad.org/help/report-an-issue/
Einleitung

KiCad is an open-source software suite for creating electronic circuit schematics and printed circuit boards (PCBs). KiCad supports an integrated design workflow in which a schematic and corresponding PCB are designed together, as well as standalone workflows for special uses. KiCad also includes several utilities to help with circuit and PCB design, including a PCB calculator for determining electrical properties of circuit structures, a Gerber viewer for inspecting manufacturing files, and an integrated SPICE simulator for inspecting circuit behavior.

KiCad runs on all major operating systems and a wide range of computer hardware. It supports PCBs with up to 32 copper layers and is suitable for creating designs of all complexities. KiCad is developed by a volunteer team of software and electrical engineers around the world with a mission of creating free and open-source electronics design software suitable for professional designers.

The latest version of this documentation is available at https://docs.kicad.org.

System Requirements

KiCad is capable of running on a wide variety of hardware and operating systems, but some tasks may be slower or more difficult on lower-end hardware. For the best experience, a dedicated graphics card and display with 1920x1080 or higher resolution is recommended.

Please check the KiCad website for the latest system requirements: https://kicad.org/help/system-requirements/

KiCad Dateien und Ordner

KiCad benutzt und erstellt folgende spezifischen Dateierweiterungen (und Ordner) für die Schaltplan und Leiterplattenbearbeitung.

Projektmanagerdatei:

| *.kicad_pro | Project file, containing settings that are shared between the schematic and PCB |
| * .pro      | Legacy (KiCad 5.x and earlier) project file. Can be read and will be converted to a .kicad_pro file by the project manager. |

Schaltplan Editor Dateien:
### Schematic Files and Libraries

<table>
<thead>
<tr>
<th>Extension</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>*.kicad_sch</td>
<td>Schematic files containing all info and the components themselves.</td>
</tr>
<tr>
<td>*.kicad_sym</td>
<td>Schematic symbol library file, containing the component descriptions: graphic shape, pins, fields.</td>
</tr>
<tr>
<td>*.sch</td>
<td>Legacy (KiCad 5.x and earlier) schematic file. Can be read and will be converted to a *.kicad_sch file on write.</td>
</tr>
<tr>
<td>*.lib</td>
<td>Legacy (KiCad 5.x and earlier) schematic library file. Can be read but not written.</td>
</tr>
<tr>
<td>*.dcm</td>
<td>Legacy (KiCad 5.x and earlier) schematic library documentation. Can be read but not written.</td>
</tr>
<tr>
<td>*.cache.lib</td>
<td>Legacy (KiCad 5.x and earlier) schematic component library cache file. Required for proper loading of a legacy schematic (.sch) file.</td>
</tr>
<tr>
<td>sym-lib-table</td>
<td>Symbol library list (<code>symbol library table</code>): list of symbol libraries available in the schematic editor.</td>
</tr>
</tbody>
</table>

### Leiterplatteneditor Dateien und Ordner:

<table>
<thead>
<tr>
<th>Extension</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>*.kicad_pcb</td>
<td>Board file containing all info but the page layout.</td>
</tr>
<tr>
<td>*.pretty</td>
<td>Footprint library folders. The folder itself is the library.</td>
</tr>
<tr>
<td>*.kicad_mod</td>
<td>Footprint files, containing one footprint description each.</td>
</tr>
<tr>
<td>*.brd</td>
<td>Legacy (KiCad 4.x and earlier) board file. Can be read, but not written, by the current board editor.</td>
</tr>
<tr>
<td>*.mod</td>
<td>Legacy (KiCad 4.x and earlier) footprint library file. Can be read by the footprint or the board editor, but not written.</td>
</tr>
<tr>
<td>fp-lib-table</td>
<td>Footprint library list (<code>footprint library table</code>): list of footprint libraries available in the board editor.</td>
</tr>
<tr>
<td>fp-info-cache</td>
<td>Cache to speed up loading of footprint libraries.</td>
</tr>
</tbody>
</table>

### Gemeinsam genutzte Dateien:

<table>
<thead>
<tr>
<th>Extension</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>*.kicad_wks</td>
<td>Page layout (drawing border and title block) description file</td>
</tr>
<tr>
<td>*.net</td>
<td>Netlist file created by the schematic, and read by the board editor. This file is associated to the .cmp file, for users who prefer a separate file for the component/footprint association.</td>
</tr>
<tr>
<td>*.kicad_prl</td>
<td>Local settings for the current project, helps Kicad remember the last used settings such as layer visibility or selection filter. May not need to be distributed with the project or put under version control.</td>
</tr>
</tbody>
</table>
**Andere Dateien:**

<table>
<thead>
<tr>
<th>Extension</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>*.cmp</td>
<td>Association between components used in the schematic and their footprints. It can be created by Pcbnew and imported by Eeschema. Its purpose is to import changes from Pcbnew to Eeschema, for users who change footprints inside Pcbnew (for instance using <em>Exchange Footprints</em> command) and want to import these changes in schematic.</td>
</tr>
</tbody>
</table>

**Andere Dateien:**

Diese Dateien werden von KiCad erstellt für die Fabrikation oder auch Dokumentation.

<table>
<thead>
<tr>
<th>Extension</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>*.gbr</td>
<td>Gerber Dateien für die Produktion der Platine.</td>
</tr>
<tr>
<td>*.drl</td>
<td>Bohrdateien (Excellon Format) für die Produktion der Platine.</td>
</tr>
<tr>
<td>*.pos</td>
<td>Positionierungsdateien (ASCII Format), für Maschinen, die die automatische Bestückung der Platine durchführen.</td>
</tr>
<tr>
<td>*.rpt</td>
<td>Report Dateien (ASCII Format), für Dokumentation.</td>
</tr>
<tr>
<td>*.ps</td>
<td>Plot Dateien (Postscript), für Dokumentation.</td>
</tr>
<tr>
<td>*.pdf</td>
<td>Plot Dateien (PDF Format), für Dokumentation.</td>
</tr>
<tr>
<td>*.svg</td>
<td>Plot Dateien (SVG Format), für Dokumentation.</td>
</tr>
<tr>
<td>*.dxf</td>
<td>Plot Dateien (DXF Format), für Dokumentation.</td>
</tr>
<tr>
<td>*.plt</td>
<td>Plot Dateien (HPGL Format), für Dokumentation.</td>
</tr>
</tbody>
</table>

**Storing and sending KiCad files**

KiCad schematic and board files contain all the schematic symbols and footprints used in the design, so you can back up or send these files by themselves with no issue. Some important design information is stored in the project file (*.kicad_pro*), so if you are sending a complete design, make sure to include it.

Some files, such as the project local settings file (*.kicad_prl) and the *fp-info-cache* file, are not necessary to send with your project. If you use a version control system such as Git to keep track of your KiCad projects, you may want to add these files to the list of ignored files so that they are not tracked.
Installing and Upgrading KiCad

Importing settings

Each major release of KiCad has its own configuration, so that you may run multiple KiCad versions on the same computer without the configurations interfering. The first time you run a new version of KiCad, you will be asked how to initialize the settings:

If a previous version of KiCad is detected, you will have the option to import the settings from that version. The location of the previous configuration files is detected automatically, but you may override it to choose another location if desired.

By default, the schematic symbol and footprint library tables from the previous version of KiCad will also be imported. If you would like to start with no library configuration, uncheck the **Import library configuration from previous version** checkbox.

You may also choose to start with default settings if you do not want to import settings from a previous version.

KiCad stores the settings files in a folder inside your user directory. Each KiCad version will store its settings in a subfolder of that folder (except for KiCad 5.1 and earlier, which did not use subfolders). Those folders are:

<table>
<thead>
<tr>
<th>Platform</th>
<th>Location</th>
</tr>
</thead>
<tbody>
<tr>
<td>Windows</td>
<td>%APPDATA%\kicad</td>
</tr>
<tr>
<td>Linux</td>
<td>~/.config/kicad</td>
</tr>
<tr>
<td>Mac OS</td>
<td>/Users/&lt;username&gt;/Library/Preferences/kicad</td>
</tr>
</tbody>
</table>
Migrating files from previous versions

Modern versions of KiCad can open files created in earlier versions, but can only write files in the latest formats. This means that in general, there are no special steps to migrate files from a previous version besides opening the files. In some cases, the file extension for a file has changed from one KiCad version to the next. After opening these files, they will be saved in the new format with the new file extension. The old files will not be deleted automatically.

In general, files created or modified by one version of KiCad cannot be opened by older versions of KiCad. For this reason, it is important to keep backup copies of your projects when testing a new KiCad release, until you are confident that you will not need to use the older KiCad version anymore.

**NOTE**

Hotkey configurations are not imported from previous versions at this time. You can manually import hotkey configurations by copying the various *.hotkeys files from the old version configuration directory to the new one. If you do so, please note that KiCad will not automatically detect conflicts such as one key being assigned to multiple actions.
Using KiCad project manager

KiCad project manager (kicad or kicad.exe) is a tool which can easily run the other tools (schematic and board editors, Gerber viewer and utility tools) when creating a design.

Das Starten der jeweiligen Tools aus dem KiCad Projektmanager heraus hat einige Vorteile:

- Quervergleiche zwischen Schaltplaneditor und Platineneditor
- Synchronization of the design between the schematic editor and board editor (without creating netlist files)

KiCad currently only supports having one project open at a time. When running the schematic and board editors from the KiCad project manager, you can only edit the schematics and board associated with the open project. When these tools are run in *stand alone* mode, you can open any file in any project, but cross probing between tools can give strange results.

Project manager window

The KiCad project manager window is composed of a tree view on the left showing the files associated with the open project, and a launcher on the right containing shortcuts to the various editors and tools.

Die Projektübersicht

The tree view shows a list of files inside the project folder. Double-clicking on a file in the tree view will open it in the associated editor. Right-clicking on a file will open a context menu with some file manipulation commands.
NOTE Only files that KiCad understands how to open are displayed in the project tree view.

Side toolbar
The toolbar on the left side of the window provides shortcuts for common project operations:

<table>
<thead>
<tr>
<th>Icon</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>📖</td>
<td>Create a new project.</td>
</tr>
<tr>
<td>📝</td>
<td>Open an existing project.</td>
</tr>
<tr>
<td>📦</td>
<td>Create a zip archive of the whole project. This includes schematic files, libraries, PCB, etc.</td>
</tr>
<tr>
<td>📦</td>
<td>Extract a project zip archive into a directory. Files in the destination directory will be overwritten.</td>
</tr>
<tr>
<td>⚡️</td>
<td>Refresh the tree view, to detect changes made on the filesystem.</td>
</tr>
<tr>
<td>📗</td>
<td>Open the project working directory in a file explorer.</td>
</tr>
</tbody>
</table>

Creating a new project
Most KiCad designs start with the creation of a project. There are two ways to create a project from the KiCad project manager: you may create an empty project, or create a project based on an existing template. This section will cover the creation of a new, empty project. Creating projects from templates is covered in the Project Templates section.

To create a new project, use the New Project... command in the File menu, click the New Project button in the top toolbar, or use the keyboard shortcut (Ctrl+N by default).

You will be prompted for a name to give your project. By default, a directory will be created for your project with the same name. For example, if you enter the name MyProject, KiCad will create the directory MyProject and the project file MyProject/MyProject.kicad_pro inside it.

If you already have a directory to store your project files in, you can uncheck the Create a new directory for the project checkbox in the New Project dialog.

NOTE It is strongly recommended that you store each KiCad project inside its own directory.

Once you select the name of your project, KiCad will create the following files inside the project directory:
**Importing a project from another EDA tool**

KiCad is able to import files created by some other software packages. Currently the following types of project are supported:

<table>
<thead>
<tr>
<th>Extension</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>*.sch, *.brd</td>
<td>Eagle 6.x or newer (XML format)</td>
</tr>
<tr>
<td>*.csa, *.cpa</td>
<td>CADSTAR archive format</td>
</tr>
</tbody>
</table>

To import a project from one of these tools, choose the appropriate option from the **Import Non-KiCad Project** submenu of the **File** menu.

You will be prompted to select either a schematic or a board file in the import file browser dialog. The imported schematic and board files should have the same base file name (e.g. project.sch and project.brd). Once the requested files are selected, you will be asked to select a directory to store the resulting KiCad project.
KiCad configuration

The KiCad preferences can always be accessed from the Preferences menu, or by using the hotkey (default Ctrl+,). The Preferences dialog is shared between the running KiCad tools. Some preferences apply to all tools, and some are specific to a certain tool (such as the schematic or board editor).

Common preferences

Accelerated graphics antialiasing: KiCad can use different methods to prevent aliasing (jagged lines) when rendering using a graphics card. Different methods may look better on different hardware, so you may want to experiment to find the one that looks best to you.

Fallback graphics antialiasing: KiCad can also apply antialiasing when using the fallback graphics mode. Enabling this feature may result in poor performance on some hardware.

Text editor: Choose a text editor to use when opening text files from the project tree view.

PDF viewer: Choose a program to use when opening PDF files.

Show icons in menus: Enables icons in drop-down menus throughout the KiCad user interface.

NOTE: Icons in menus are not displayed on some operating systems.

Icon theme: Sets whether to use the icon theme designed for light window backgrounds or dark window backgrounds. The default setting of Automatic will choose the theme based on the lightness of the operating system window theme.

Icon scale: Sets the size of the icons used in menus and buttons throughout KiCad. Choose Automatic to pick an appropriate icon scale automatically based on your operating system settings.

Canvas scale: Sets the scale of the drawing canvas used in the KiCad editors. Choose Automatic to pick an appropriate canvas scale automatically based on your operating system settings.
Apply icon scaling to fonts: This setting will scale fonts used in the UI according to the icon scale setting. This is not needed for most users, but may improve the look of KiCad on certain Linux platforms when using a high-DPI display.

Warp mouse to origin of moved object: When enabled, the mouse cursor will be repositioned (warped) to the origin of an object when you start a move command on that object.

First hotkey selects tool: When disabled, pressing the hotkey for a command such as Add Wire will immediately start the command at the current cursor location. When enabled, pressing the hotkey the first time will just select the Add Wire tool but will not immediately begin a wire.

Remember open files for next project launch: When enabled, KiCad will automatically re-open any files that were previously open when a project is re-opened.

Auto save: When editing schematics and board files, KiCad can automatically save your work periodically. Set to 0 to disable this feature.

File history size: Configure the number of entries in the list of recently-opened files

3D cache file duration: KiCad creates a cache of 3D models in order to speed up the 3D viewer. You can configure how long to keep this cache before deleting old files.

Automatically backup projects: When enabled, KiCad projects will be archived to ZIP files automatically according to the settings below. The archives will be stored in a subfolder of the project folder. Backups are created when saving files in the project.

Create backups when auto save occurs: When enabled, a backup will be created every time an automatic file save occurs (if the backup is permitted by the settings below). This setting has no effect if the auto save interval is set to 0 (disabled).

Maximum backups to keep: When creating a new backup, the oldest backup file will be deleted to keep the total number of backup files below this limit.

Maximum backups per day: When creating a new backup, the oldest backup file created on the current day will be deleted to stay below this limit.

Minimum time between backups: If backup is triggered (for example, by saving a board file), the backup will not be created if an existing backup file is newer than this limit.

Maximum total backup size: When creating a new backup file, the oldest backup files will be deleted to keep the total size of the backup files directory below this limit.

Remember open files for next project launch: When checked, KiCad will re-open the schematic and board editor if they were open the last time you closed the project manager.
Mouse and touchpad preferences

Center and warp cursor on zoom: When enabled, zooming using the hotkeys or mouse wheel will cause the view to be centered on the cursor location.

Use zoom acceleration: When enabled, scrolling the mouse wheel or touchpad faster will cause the zoom to change faster.

Zoom speed: Controls how much the zoom changes for a given amount of scrolling the mouse wheel or touchpad. Use Automatic to set a default value depending on your operating system.

Automatically pan while moving object: When enabled, the view can be panned while moving an object by moving close to the edge of the canvas.

Auto pan speed: Controls how fast the canvas pans while moving an object.

Mouse buttons: You can set the behavior of dragging the middle and right mouse buttons to zoom the view, pan the view, or have no effect. You can also set the behavior of dragging the left mouse button depending on whether or not any objects are already selected in the editing canvas.

NOTE | The left mouse button is always used for selecting and manipulating objects.

Mouse wheel and touchpad scrolling: You can set the behavior of scrolling the mouse wheel or vertical motion of the touchpad while pressing certain modifier keys.

Pan left/right with horizontal movement: When enabled, you can pan the view using the touchpad or horizontal scroll wheel (if present on your mouse).
Hotkey preferences

You can use this dialog to customize the hotkeys used to control KiCad. The hotkeys in the Common section are shared between every KiCad program. Hotkeys for each specific KiCad program are shown when that program is running. You can assign the same hotkey to a different action in different KiCad programs (for example, the schematic editor and the board editor), but you cannot assign a hotkey to more than one action in the same program.

There are many available commands, and so not all of them have a hotkey assigned by default. You can add a hotkey to any command by double-clicking on the command in the list. If you choose a hotkey that is already assigned to a different command, you can choose to use that hotkey on your chosen command, which will remove the hotkey assignment from the conflicting command.

Changes that you have made to hotkey assignments are shown with a * character at the end of the command name. You can undo changes to a specific command by right-clicking that command and selecting Undo Changes, or you can undo all changes with the button below the command list.

Importing hotkeys

Hotkey preferences are stored in .hotkeys files in the KiCad settings directory (see the Settings section for information about where the settings directory is on your operating system). If you have configured KiCad hotkeys the way you like on one computer, you can transfer that configuration to another computer by importing the appropriate .hotkeys file(s).

Paths configuration

In KiCad können manche Pfade durch Umgebungsvariablen definiert werden. Einige der Umgebungsvariablen werden intern durch KiCad gesetzt, und können benutzt werden, um Pfade zu definieren (für Bibliotheken, 3D-Formen, und mehr).
This is useful when absolute paths are not known or are subject to change (e.g. when you transfer a project to a different computer), and also when one base path is shared by many similar items. Consider the following which may be installed in varying locations:

- Schematic symbol libraries
- Footprint libraries
- 3D-Formen die in den Footprint Definitionen benutzt werden

For instance, the path to the `connect.pretty` footprint library, when using the `KISYSMOD` environment variable, would be defined as `$KISYSMOD/connect.pretty`

The Preferences → Configure Paths... menu allows you to define paths for some built-in KiCad environment variables, and add your own environment variables to define personal paths, if needed.

### KiCad Umgebungsvariablen:

<table>
<thead>
<tr>
<th>Variable</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>KICAD6_SYMBOL_DIR</td>
<td>Base path of symbol library files.</td>
</tr>
<tr>
<td>KICAD6_FOOTPRINT_DIR</td>
<td>Base path of footprint library files.</td>
</tr>
<tr>
<td>KICAD6_3DMODEL_DIR</td>
<td>Base path of 3D models used in footprints.</td>
</tr>
<tr>
<td>KICAD6_TEMPLATE_DIR</td>
<td>Location of project templates installed with KiCad.</td>
</tr>
<tr>
<td>KICAD_USER_TEMPLATE_DIR</td>
<td>Location of personal project templates.</td>
</tr>
<tr>
<td>KICAD6_SCRIPTING_DIR</td>
<td>Location of Python scripts installed with KiCad.</td>
</tr>
<tr>
<td>KICAD6_USER_SCRIPTING_DIR</td>
<td>Location of personal Python scripts.</td>
</tr>
</tbody>
</table>

**NOTE** You cannot override an environment variable that has been set outside of KiCad by using the Configure Paths dialog. Any variable that has been set externally will be shown as read-only in the dialog.

Some advanced environment variables can be set to customize KiCad’s behavior. These variables are not shown in the environment variable configuration dialog by default. Changing these variables will not result in KiCad moving any files from the default location to the new location, so if you change these variables you will need to copy any desired settings or files manually.
Additional environment variables:

<table>
<thead>
<tr>
<th>Environment Variable</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>KICAD_CONFIG_HOME</td>
<td>Base path of KiCad configuration files. Subdirectories will be created within this directory for each KiCad minor version.</td>
</tr>
<tr>
<td>KICAD_DOCUMENTS_HOME</td>
<td>Base path of KiCad user-modifiable documents, such as templates, Python scripts, libraries, etc. Subdirectories will be created within this directory for each KiCad minor version.</td>
</tr>
</tbody>
</table>

Beachten Sie ebenso die Umgebungsvariable KIPRJMOD, die immer intern durch KiCad definiert ist und den aktuellen absoluten Projekt Pfad abbildet.

Zum Beispiel, ${KIPRJMOD}/connect.pretty ist immer der Ordner connect.pretty (die pretty Footprint Bibliothek) der innerhalb des aktuellen Projektes liegt.

Wenn Sie die Konfiguration von Pfaden verändern, beenden und starten Sie KiCad neu, um mögliche Fehler bei der Pfad Benutzung zu verhindern.

Libraries configuration

The Preferences → Manage Symbol Libraries... menu let you manage the library list files called symbol library table (sym-lib-table).

Likewise, use the Preferences → Manage Footprint Libraries... menu to manage the library list files called footprint library table (fp-lib-table).

There are 2 library list files: the first (located in the user home directory) is global for all projects and the second (located in the project directory) is optional and specific to the project.
**Projekt Vorlagen:**

Using a project template facilitates setting up a new project with predefined settings. Templates may contain pre-defined board outlines, connector positions, schematic elements, design rules, etc. Complete schematics and/or PCBs used as seed files for the new project may even be included.

**Using templates**

Das Menü **Datei → Neues Projekt → Projekt aus einer Vorlage** wird den Dialog zur Auswahl der Projektvorlage öffnen:

A single click on a template's icon will display the template information, and a further click on the OK button creates the new project. The template files will be copied to the new project location and renamed to reflect the new project's name.

Nach der Auswahl einer Vorlage:
Raspberry Pi

Expansion Board

This project template is the basis of an expansion board for the Raspberry Pi $25 ARM board.

This base project includes a PCB edge defined as the same size as the Raspberry-Pi PCB with the connectors placed correctly to align the two boards. All IO present on the Raspberry-Pi board is connected to the project through the 0.1" expansion headers.

The board outline looks like the following:

Ablageorte von Vorlagen:

KiCad looks for template files in the following paths:

- path defined in the environment variable KICAD_USER_TEMPLATE_DIR
- path defined in the environment variable KICAD_TEMPLATE_DIR
- Systemweite Vorlagen: <kicad bin dir>../share/template/ oder auch /usr/share/kicad/template/
- Benutzer definierte Vorlagen:
  - Unix: ~/kicad/template/
  - Windows: C:\Documents and Settings\username\My Documents\kicad\template or C:\Users\username\Documents\kicad\template
  - Mac: ~/Documents/kicad/template/
Erstellen von Vorlagen

The template name is the directory name where the template files are stored. The metadata directory is a subdirectory named *meta* containing files describing the template.


All files and directories in a template are copied to the new project path when a project is created using a template, except *meta*. Files and directories containing the template name will be renamed with the new project file name.

For example, creating a project called *newproject* from a template named *example*:

<table>
<thead>
<tr>
<th>Files in template <em>example</em> directory</th>
<th>Files created in project <em>newproject</em> directory</th>
</tr>
</thead>
<tbody>
<tr>
<td>example.kicad_pro</td>
<td>newproject.kicad_pro</td>
</tr>
<tr>
<td>example.kicad_sch</td>
<td>newproject.kicad_sch</td>
</tr>
<tr>
<td>example.kicad_pcb</td>
<td>newproject.kicad_pcb</td>
</tr>
<tr>
<td>example-first.kicad_sch</td>
<td>newproject-first.kicad_sch</td>
</tr>
<tr>
<td>second-example.kicad_sch</td>
<td>second-newproject.kicad_sch</td>
</tr>
<tr>
<td>third.kicad_sch</td>
<td>third.kicad_sch</td>
</tr>
<tr>
<td>third.kicad_pcb</td>
<td>third.kicad_pcb</td>
</tr>
</tbody>
</table>

A template does not need to contain a complete project, if a required project file is missing, KiCad will create it using its default create project behavior:

<table>
<thead>
<tr>
<th>Files in template <em>example</em> directory</th>
<th>Files created in <em>newproject</em> directory</th>
</tr>
</thead>
<tbody>
<tr>
<td>example.kicad_sch</td>
<td>newproject.kicad_sch</td>
</tr>
<tr>
<td>first-example.kicad_sch</td>
<td>first-newproject.kicad_sch</td>
</tr>
<tr>
<td>first-example.kicad_pcb</td>
<td>first-newproject.kicad_pcb</td>
</tr>
<tr>
<td>second-example.kicad_sch</td>
<td>second-newproject.kicad_sch</td>
</tr>
<tr>
<td>second-example.kicad_pcb</td>
<td>second-newproject.kicad_pcb</td>
</tr>
<tr>
<td>third.kicad_sch</td>
<td>newproject.kicad_pro (default)</td>
</tr>
<tr>
<td>third.kicad_pcb</td>
<td>newproject.kicad_pcb (default)</td>
</tr>
</tbody>
</table>

As an exception to the template name renaming rule, if one project file (.kicad_pro) exists and its name doesn't match the template name, KiCad will do the renaming based on that project file name instead:
### Template example

Here is an example showing project files for **raspberry-pi-gpio** template:

```
    + template
        + Arduino_As_Uno_R3
        + Arduino_Fio
        + Arduino_Mega_R3
        + Arduino_Micro
        + Arduino_Mini
        + Arduino_Nano
        + Arduino_Pro_Mini
        + BeagleBone-Black-Cape
        + raspberry-pi-gpio
            + meta
                + raspberry-pi-gpio.cmp
                + raspberry-pi-gpio.kicad_pcb
                + raspberry-pi-gpio.net
                + raspberry-pi-gpio.pro
                + raspberry-pi-gpio.sch
                + raspberry-pi-gpio.stf
                + raspberry-pi-gpio-cache.lib
```

Und die Dateien mit den Metadaten:

```
    + raspberry-pi-gpio
        + meta
            + brd.png
            + icon.png
            + info.html
```

### Benötigte Dateien:

| meta/info.html | HTML formatierte Information, welche die Vorlage beschreibt. |
The `<title>` tag determines the actual name of the template that is exposed to the user for template selection. Note that the project template name will be cut off if it's too long.

Durch die Benutzung von HTML ist es möglich, dass Bilder einfach eingebunden werden können, ohne das neue Schemata erstellt werden müssen. Es können nur Basis HTML Tags in diesem Dokument benutzt werden.

Und hier das Beispiel für eine Datei `info.html`:

```html
<!DOCTYPE HTML PUBLIC "-//W3C//DTD HTML 4.0 Transitional//EN">
<html>
<head>
<meta http-equiv="content-type" content="text/html; charset=windows-1252">
<title>Raspberry Pi - Expansion Board</title>
</head>
<body lang="fr-FR" dir="ltr">
This project template is the basis of an expansion board for the Raspberry Pi $25 ARM board.
This base project includes a PCB edge defined as the same size as the Raspberry-Pi PCB with the connectors placed correctly to align the two boards. All IO present on the Raspberry-Pi board is connected to the project through the 0.1" expansion headers.
The board outline looks like the following:

(c)2012 Brian Sidebotham
(c)2012 KiCad Developers
```

Optionale Dateien:

<table>
<thead>
<tr>
<th>Datei</th>
<th>Beschreibung</th>
</tr>
</thead>
<tbody>
<tr>
<td>meta/icon.png</td>
<td>Eine PNG Grafik mit 64x64 Pixel, welche als anklickbares Icon im Auswahldialog der Vorlagen verwendet wird.</td>
</tr>
</tbody>
</table>

Jede weitere Grafik, die in `meta/info.html` benutzt wird, wie zum Beispiel das Bild des Leiterplattendesign von oben, wird ebenfalls in diesem Ordner abgelegt.
Plugin and Content Manager

NOTE | TODO: Write this section